

**AMENDMENTS TO THE SPECIFICATION**

On page 4, in the Brief Description of the Drawings, please insert at the end:

--Figure 6 represents a cross-section of an actuator.--

On page 5, please amend the first paragraph as follows:

--Figure 1, and Figure 3 and Figure 6 show an actuator 1 with a shaft 2 and a shift finger 3. The shift finger can be shifted in an axial direction A-A and can be rotated relative to the axis A-A. The shaft 2 is supported in the bearing 4 with rotational as well as axial mobility. To this end, a sliding sleeve 5 is arranged in a bearing seat 4, which can be permanently connected to the transmission housing. The shaft 2 is equipped at one end with an arrangement of drive motors 10, 11, which can be energized by an electronic control unit to drive the axial and rotational movements of the shaft 2 or shift finger 3.--

On page 9, please replace the paragraph beginning "According to a further inventive concept..." with the following rewritten paragraph.

--According to a further inventive concept, it can also be practical to arrange the grooves in the sleeves rather than on the shaft, in which case the guide pins would be arranged on the shaft. As shown in Figure 6, the shaft 2 has outward directed guide pins 32a and 33a, while the sleeves 20 and 21 have internal helical grooves 40a and 41a of respectively opposite pitch, with pin 32a engaging groove 40a and pin 33a engaging groove 41a.--